STATISTICAL DEPTH: PART II: DEPTH IN MATHEMATICS

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STATISTICAL DEPTH

Consider the depth of $x \in \mathbb{R}^d$ w.r.t. $P \in \mathcal{P}(\mathbb{R}^d)$ $D \colon \mathbb{R}^d \times \mathcal{P}(\mathbb{R}^d) \to [0, 1] \colon (x, P) \mapsto D(x; P).$



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HALFSPACE DEPTH

Halfspace depth (Tukey, 1975) of $x \in \mathbb{R}^d$

$$hD(x; P) = \inf_{H \in \mathcal{H}(x)} P(H).$$



Statistical depth is a function

$$D: \mathbb{R}^d \times \mathcal{P}\left(\mathbb{R}^d\right) \to [0,1]: (x,P) \mapsto D(x;P),$$

that satisfies (Zuo and Serfling, 2000b)

- 1. affine invariance;
- 2. maximality at the centre for symmetric distributions;
- 3. monotonicity relative to the depth median;
- 4. vanishing at infinity.

Sometimes it is required also (Serfling, 2006b)

- 5. upper semi-continuity as a function of *x*;
- 6. continuity as a functional of *P*;
- 7. quasi-concavity in x.

Symmetry of random variables

Depth of a median — Grünbaum's theorem Measures of symmetry Funk's characterization of symmetry

Quasi-Concavity: Floating body Dupin's floating body Convex floating body

Symmetry of random variables

CONVEX BODIES

Convex body is a non-empty, compact and convex set $K \subset \mathbb{R}^d$. We write also $K \in \mathcal{K}^d$ (Webster, 1994; Schneider, 2014).



CONVEX BODIES

Star body is $K \subset \mathbb{R}^d$, such that for some $x \in K$ and any $k \in K$ it holds $[x, k] \subset K$. (Schneider, 2014; Groemer 1996).



SYMMETRY OF CONVEX BODIES

A convex body $K \in \mathcal{K}^d$ is (centrally) symmetric about $\theta \in \mathbb{R}^d$ iff

$$K-\theta=-(K-\theta).$$



Symmetry of distributions

$X \sim P \in \mathcal{P}(\mathbb{R})$ is (centrally) symmetric about $\theta \in \mathbb{R}$ iff

$$X-\theta\stackrel{d}{=}-(X-\theta).$$



 $X \sim P \in \mathcal{P}(\mathbb{R})$ is (centrally) symmetric about $\theta \in \mathbb{R}$ iff

$$X-\theta \stackrel{d}{=} -(X-\theta).$$

Multiple generalizations to $\mathcal{P}\left(\mathbb{R}^{d}\right)$ (Serfling, 2006):

- ► spherical symmetry;
- elliptical symmetry;
- central symmetry;
- angular symmetry (Liu, 1988);
- halfspace symmetry (Zuo and Serfling, 2000).

SPHERICAL SYMMETRY

 $X \sim P \in \mathcal{P}(\mathbb{R}^d)$ is spherically symmetric about $\theta \in \mathbb{R}^d$ iff $X - \theta \stackrel{d}{=} A(X - \theta)$

for any $A \in \mathbb{R}^{d \times d}$ orthogonal.



 $X \sim P \in \mathcal{P}(\mathbb{R}^d)$ is elliptically symmetric about $\theta \in \mathbb{R}^d$ iff $X \stackrel{d}{=} A^T Y + \theta$

for $Y \in \mathbb{R}^k$ spherically symmetric, and $A \in \mathbb{R}^{k \times d}$ of rank $k \ (\leq d)$.



CENTRAL SYMMETRY

$X \sim P \in \mathcal{P}(\mathbb{R}^d)$ is centrally symmetric about $\theta \in \mathbb{R}^d$ iff

$$X-\theta \stackrel{d}{=} -(X-\theta).$$



CENTRAL SYMMETRY

$X \sim P \in \mathcal{P}(\mathbb{R}^d)$ is centrally symmetric about $\theta \in \mathbb{R}^d$ iff $\langle X - \theta, u \rangle$ are (centrally) symmetric for all $u \in \mathbb{S}^{d-1}$.



ANGULAR SYMMETRY

$X \sim P \in \mathcal{P}(\mathbb{R}^d) \text{ is angularly symmetric about } \theta \in \mathbb{R}^d \text{ iff (Liu, 1988)}$ $\frac{X - \theta}{\|X - \theta\|} \stackrel{d}{=} -\frac{X - \theta}{\|X - \theta\|}. \quad (\text{here } 0/0 = 0)$



ANGULAR SYMMETRY

$X \sim P \in \mathcal{P}(\mathbb{R}^d)$ is angularly symmetric about $\theta \in \mathbb{R}^d$ iff (Liu, 1988) $\frac{X - \theta}{\|X - \theta\|}$ is centrally symmetric about 0.



HALFSPACE SYMMETRY

 $X \sim P \in \mathcal{P}(\mathbb{R}^d)$ is halfspace symmetric about $\theta \in \mathbb{R}^d$ iff (Zuo and Serfling, 2000)

 $hD(\theta; P) \ge 1/2.$



HALFSPACE SYMMETRY

$X \sim P \in \mathcal{P}(\mathbb{R}^d)$ is halfspace symmetric about $\theta \in \mathbb{R}^d$ iff $\langle \theta, u \rangle$ is a median of $\langle X, u \rangle$ for all $u \in \mathbb{S}^{d-1}$.



Proposition (Zuo and Serfling, 2000) In the space of probability measures $\mathcal{P}(\mathbb{R}^d)$

spherical symmetry \implies elliptical symmetry \implies central symmetry \implies angular symmetry \implies halfspace symmetry.

No implication can be reversed.

$\mathsf{Central} \implies \mathsf{angular} \implies \mathsf{halfspace symmetry}$

central symmetry \nleftrightarrow angular symmetry



angular symmetry \Leftarrow halfspace symmetry



angular symmetry \nleftrightarrow halfspace symmetry



Proposition (Zuo and Serfling, 2000, Theorem 2.6) Suppose a random vector X is halfspace symmetric about a unique point $\theta \in \mathbb{R}^d$, end either

1. X is absolutely continuous, or

2. X is discrete and $P(X = \theta) = 0$.

Then X is angularly symmetric about θ .

Remark. The centre of halfspace symmetry of $X \sim P \in \mathcal{P}(\mathbb{R}^d)$ is a unique point, unless d = 1 and X has two medians.

NON-SYMMETRIC DISTRIBUTION

Distribution which is not halfspace symmetric:

 $\sup_{x\in\mathbb{R}^2} hD(x;P) = 4/9$



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 $\begin{array}{l} \text{H-symmetry} \supsetneq \text{A-symmetry} \supsetneq \text{C-symmetry} \supsetneq \text{E-symmetry} \urcorner \cr \\ \text{S-symmetry} \end{array}$

A desired property of the data depth:

2. maximality at the centre for symmetric distributions;

Proposition (Zuo and Serfling, 2000b) For $X \sim P \in \mathcal{P}(\mathbb{R}^d)$ symmetric about $\theta \in \mathbb{R}^d$

$$hD(\theta; P) = \sup_{x \in \mathbb{R}^d} hD(x; P).$$

Depth of a median

Testing for H-symmetry of $P \in \mathcal{P}(\mathbb{R}^d)$ (Dutta et al., 2011)

$$T_n = \left(1/2 - \sup_{x \in \mathbb{R}^d} hD(x; P_n)\right)_+$$



MINIMUM DEPTH OF THE MEDIAN

For $P \in \mathcal{P}(\mathbb{R}^d)$ uniform in the vertices of a simplex (Donoho and Gasko, 1992)



For $X \sim P$ angularly symmetric about $\theta \in \mathbb{R}^d$ (Rousseeuw and Struyf, 2004, Theorem 1)

 $\sup_{x\in\mathbb{R}^d} hD(x; P) = hD(\theta, P) = 1/2 + P(\{\theta\})/2.$



Problem (Donoho and Gasko, 1992; Dutta et al., 2011)

The depth of a median of an absolutely continuous distribution in \mathbb{R}^d lies in the interval [1/(d+1), 1/2]. Can we say more?

DEPTH OF CONVEX BODIES

Population depth of a convex body $K \in \mathcal{K}^d$



$$K + L = \{x + y \colon x \in K, y \in L\}, \quad \lambda K = \{\lambda x \colon x \in K\}$$



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Proposition (Brunn, 1887; Minkowski, 1896) Let $K, L \subset \mathbb{R}^d$ be convex bodies, vol (K) = vol(L) = 1. Then vol $((K + L)/2) \ge 1$, with equality iff K is a translate of L.

► Function $K \mapsto \text{vol}(K)^{1/d}$ is concave on \mathcal{K}^d .

Proposition (Grünbaum, 1960) Let $K \in \mathcal{K}^d$, vol (K) = 1. Then there is a point $x \in K$ such that

$$hD(x; K) \ge \left(\frac{d}{d+1}\right)^d$$

The bound is attained iff K is a simplex.

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 ➤ Grübaum proves a stronger statement: The theorem holds with x = E K.
 ➤ lim_{d→∞} (^d/_{d+1})^d = exp(-1) ≈ 0.37.

Proposition (Winternitz, 1917) For $K \in \mathcal{K}^2$ with centroid $x \in K$

$$hD(x; K) \ge 4/9 = \left(\frac{2}{2+1}\right)^2.$$

This bound is attained iff K is a triangle.

Arthur Winternitz (1893 - 1961)

- graduated (1917) and worked (1917 1939) at the German University in Prague;
- ▶ the Winternitz theorem first appears in Blaschke (1923);
- independently rediscovered by
 - 1935 Lavrentjev and Lyusternik;
 - 1945 Neumann;
 - 1951 Yaglom and Boltyanskii;
 - 1955 Ehrhart;
 - 1958 Newman;
- > Theorem extended to d = 3 by Ehrhart (1956);
- For general *d* conjectured by Ehrhart (1955), proved independently by Grünbaum (1960) and Hammer (1960).

Version with $P \in \mathcal{P}(\mathbb{R}^d)$ (Donoho and Gasko, 1992):

$$\sup_{x\in\mathbb{R}^d}hD(x;P)\geq\frac{1}{d+1}.$$

Previously noted by

- Neumann (1955), Yaglom and Boltyanskii (1951), Newman (1958) for d = 2;
- ▶ Rado (1946), Birch (1959), Grünbaum (1960) for all *d*;
- Grünbaum (1960) shows that the bound is attained iff P is uniform in the vertices of a simplex.

Definition (Borell, 1974) For $\kappa \in [-\infty, \infty)$ we say that $P \in \mathcal{P}(\mathbb{R}^d)$ is a κ -concave measure iff

$$P(\lambda A + (1 - \lambda)B) \ge \begin{cases} P(A)^{\lambda} P(B)^{1 - \lambda} & \text{for } \kappa = 0, \\ \min\{P(A), P(B)\} & \text{for } \kappa = -\infty, \\ (\lambda P(A)^{\kappa} + (1 - \lambda)P(B)^{\kappa})^{1/\kappa} & \text{otherwise.} \end{cases}$$

for all $A, B \subset \mathbb{R}^d$ Borel and $\lambda \in [0, 1]$.

For a κ -concave measure $P \in \mathcal{P}(\mathbb{R}^d)$:

- ▶ for any $\tau < \kappa$ is *P* also τ -concave;
- ▶ if $\kappa > 1$, *P* must be a Dirac measure;
- ▶ uniform measures on convex bodies are 1/*d*-concave;
- ▶ if *P* has a density, then $\kappa \leq 1/d$;
- ▶ if $\kappa = 0$, *P* is called log-concave;
- ▶ if $\kappa > -1$, then *P* has a mean value;
- ▶ if $\kappa = -\infty$, *P* is called quasi-concave.

WINTERNITZ THEOREM FOR CONCAVE MEASURES

Proposition (Bobkov, 2010, Theorem 5.2) For $\kappa \in (-1, 1]$ and κ -concave $X \sim P \in \mathcal{P}(\mathbb{R}^d)$

$$hD(\mathsf{E}X; \mathsf{P}) \geq \begin{cases} \exp(-1) & \text{for } \kappa = 0, \\ \left(\frac{1}{1+\kappa}\right)^{1/\kappa} & \text{otherwise.} \end{cases}$$

There are κ -concave measures that attain this bound.

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There are κ -concave measures that attain this bound.

Problem

Can we say something about the case $\kappa \leq -1$? What about points other than EX?

Note: For $\kappa = 0$ the theorem was already known in economics. (Caplin and Nalebuff, 1988)















Proposition (Winternitz, 1917) For $K \in \mathcal{K}^2$ with centroid $x \in K$

$$hD(x; K) \ge 4/9 = \left(\frac{2}{2+1}\right)^2$$
.

This bound is attained iff K is a triangle.

Definition (Winternitz, 1917; Blaschke, 1923) For $K \in \mathcal{K}^d$, $x \in K$ and a halfspace $H \in \mathcal{H}(x)$, consider

$$f(H, x) = \frac{\operatorname{vol}(K \cap H)}{\operatorname{vol}(K) - \operatorname{vol}(K \cap H)}$$

and $f(x) = \min \{f(H, x) : H \in \mathcal{H}(x)\}$. The Winternitz measure of symmetry of the body *K* is then given by

 $F(K) = \max \left\{ f(x) \colon x \in K \right\}.$

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$$F(K) = \max \left\{ f(x) \colon x \in K \right\}.$$

$$f(x) = \frac{hD(x; K)}{1 - hD(x; K)}$$

Definition (Grünbaum, 1963)

A function s: $\mathcal{K}^d \rightarrow [0, 1]$ is called a measure of symmetry iff

- 1. s(K) = 1 iff K has a centre of (central) symmetry;
- 2. s(K) = s(T(K)) for every $K \in \mathcal{K}^d$ and every non-singular affine transformation $T: \mathbb{R}^d \to \mathbb{R}^d$;
- 3. s is continuous on \mathcal{K}^d .

For $K \in \mathcal{K}^d$, $x \in K$ $D(x; K) = \inf_{H \in \mathcal{H}(x)} \frac{\operatorname{dist}(\partial H, \partial H_1)}{\operatorname{dist}(\partial H, \partial H_2)},$



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For $K \in \mathcal{K}^d$, $x \in K$ (Besicovitch, 1951)

$$D(X;K) = \operatorname{vol}(K \cap (2X - K)).$$



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Localization of *hD* (Paindaveine and Van Bever, 2013)


LOCAL HALFSPACE DEPTH



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LOCAL HALFSPACE DEPTH







WINTERNITZ MEASURE OF SYMMETRY





Definition (Grünbaum, 1963)

A function s: $\mathcal{K}^d \rightarrow [0, 1]$ is called a measure of symmetry iff

- > s(K) = 1 iff K has a centre of (central) symmetry;
- ► s(K) = s(T(K)) for every $K \in \mathcal{K}^d$ and every non-singular affine transformation $T: \mathbb{R}^d \to \mathbb{R}^d$;
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From the definition of the halfspace symmetry we get

Proposition A convex body is halfspace symmetric \iff it is centrally symmetric. Some history:

- > for d = 2 the problem is considered trivial;
- shown for d = 3, and conjectured for any d by Paul Funk (1913);
- fully proved only by Schneider (1970) using functional equations;
- newer proofs involve spherical integration (Falconer, 1983);
- extensions use spherical harmonics (Groemer, 1996);
- > no elementary proof known for d > 3.

For $K \in \mathcal{K}^d$: H-symmetry \iff A-symmetry \iff C-symmetry.



Proposition (Zuo and Serfling, 2000, Theorem 2.6) Suppose a random vector X is halfspace symmetric about a unique point $\theta \in \mathbb{R}^d$, end either

- 1. X is absolutely continuous, or
- 2. X is discrete and $P(X = \theta) = 0$.

Then X is angularly symmetric about θ .

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Then X is angularly symmetric about θ .

For *P* uniform on $K \in \mathcal{K}^d$ this implies Funk's characterization! (for convex (star) bodies angular symmetry \equiv central symmetry) Proof only for d = 2, for the sake of simplicity (p. 73).



Proposition (Dutta et al., 2011, Theorem 2) Suppose a random vector X is halfspace symmetric about $\theta \in \mathbb{R}^d$. Then X is angularly symmetric about θ .

Proposition (Dutta et al., 2011, Theorem 2) Suppose a random vector X is halfspace symmetric about $\theta \in \mathbb{R}^d$. Then X is angularly symmetric about θ .

Proof II: For d = 2, general case "analogous".

Proposition (Rousseeuw and Ruts, 2003, Theorem 2) *If there is a point* $\theta \in \mathbb{R}^d$ *with*

$$hD(\theta; P) = 1/2 + P(\{\theta\})/2,$$

then $X \sim P$ is angularly symmetric about θ .

IDEA OF THE PROOF (ROUSSEEUW AND STRUYF, 2004)

(i). The map $x \mapsto (x_1/|x_d|, x_2/|x_d|, \dots, x_d/|x_d|)$ takes $\mathcal{H}(0)$ to halfspaces passing through hyperplanes $H^{\pm} = \{x \in \mathbb{R}^d : x_d = \pm 1\}.$



(ii). Apply the Cramér-Wold device (Cramér and Wold, 1936) in \mathbb{R}^{d-1} .

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(ii). Apply the Cramér-Wold device (Cramér and Wold, 1936) in \mathbb{R}^{d-1} .

Proof works for any *d*, using only the Cramér and Wold device.

Proposition (Cramér and Wold, 1936) Any distribution $X \sim P \in \mathcal{P}(\mathbb{R}^d)$ is uniquely determined by the totality of its one-dimensional projections $\langle X, u \rangle$, $u \in \mathbb{S}^{d-1}$.

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First simple proof of the characterization.

As collected by Grünbaum (1963):

- ► level sets of *hD* are convex and closed;
- ▶ for any $K \in \mathcal{K}^d$ the halfspace median is unique;

Proposition (Blaschke, 1923; Grünbaum, 1963) For any convex body $K \subset \mathbb{R}^d$ whose halfspace median is $x \in K$, there exists a collection of at least d + 1 halfspaces $\{H_i\}$ such that $\bigcup_i H_i = \mathbb{R}^d$, $x \in \bigcap_i H_i$, and

$$P(H_i) = hD(x; K) = \sup_{y \in \mathbb{R}^d} hD(y; K).$$

For each such H_i the point x is the centroid of $\partial H_i \cap K$.

Call $H \in \mathcal{H}(x)$ a minimizing halfspace of $P \in \mathcal{P}(\mathbb{R}^d)$ at x if P(H) = hD(x; P),

and a hyperplane ∂H a barycentric cut of *P* at *x* if the centroid of the cut (conditional expectation) of *P* by ∂H is *x*.



Independently, it was proved in geometry/statistics:

- 1. For $K \in \mathcal{K}^d$, the boundary of any minimizing halfspace is a barycentric cut (Blaschke, 1917).
- 2. Minimizing halfspaces of the median x of $K \in \mathcal{K}^d$ cover \mathbb{R}^d . (Donoho and Gasko, 1992)

Observation / Problem (Grünbaum, 1963)

For all $K \in \mathcal{K}^d$ there exist (d + 1) barycentric cuts through the halfspace median x of P.

Helly's theorem for depth median

Problem Books in Mathematics

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Unsolved Problems in Geometry

2

A8. Sections through the centroid of a convex body. Let K be a 3dimensional convex body with centroid (i.e., center of gravity) g. Is g necessarily the centroid of at least four plane sections of K through g? Is it even the centroid of seven such sections, as is the case if K is a tetrahedron? More generally, if K is a d-dimensional convex body, is the centroid of K the centroid of d + 1 or even of $2^d - 1$ of the (d - 1)-dimensional sections through g? When d = 2 this is easily seen to be so—in this case g bisects three chords of K. This question is due to Grünbaum and Loewner, see also the earlier paper by Steinhaus.

A consequence of Helly's theorem (see Section E1) is that *some* point of K is the centroid of at least d + 1 sections by hyperplanes. What can be said about the set of points of K enjoying this property? In the plane case Ceder showed that this set is connected, but not necessarily convex. Chakerian & Stein discuss other aspects of this problem.









(Patáková, Tancer, and Wagner, 2020)



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Question: Do (d + 1) barycentric cuts pass through the halfspace median of all $K \in \mathcal{K}^d$?

(Patáková, Tancer, and Wagner, 2020)



Question: Do (d + 1) barycentric cuts pass through some point for all $K \in \mathcal{K}^d$? 99/169

As collected by Grünbaum (1963):

- level sets of hD are convex and closed;
- ▶ for any $K \in \mathcal{K}^d$ the halfspace median is unique.

In statistics, we have

Proposition (Mizera and Volauf, 2002, Proposition 7) Under conditions (S) and (C), the halfspace median of $P \in \mathcal{P}(\mathbb{R}^d)$ is unique.

The result is incomplete, the proof works only for d = 2.
Take $P \in \mathcal{P}(\mathbb{R}^3)$ the product of uniform on a triangle in \mathbb{R}^2 and Cauchy in \mathbb{R}



A measure without a unique median

Take $P \in \mathcal{P}(\mathbb{R}^3)$ the product of uniform on a triangle in \mathbb{R}^2 and Cauchy in \mathbb{R}



Proposition (Nagy, Pokorný, Laketa, 2021+) A measure $P \in \mathcal{P}(\mathbb{R}^d)$ has a unique median if

- 1. **(C)** is valid,
- 2. P has a density that is "almost continuous" on hyperplanes, and
- 3. an integrability condition is satisfied (existence of expectation).

Question: Is there a (non-convex) body $K \subset \mathbb{R}^d$ such that *P* uniform on *K* does not have a unique median?

Main messages:

- symmetry of multivariate distributions is not an easy topic;
- Grünbaum (1960) knew about the depth before Tukey (1975);
- depth of a median is a measure of symmetry;
- > many related open problems.
- ► Not mentioned:
 - Affine invariant points, (Grünbaum, 1963; Meyer et al., 2015, 2015b)
 - Dimensionality of depth regions.
 (Pokorný et al., 2021+)

QUASI-CONCAVITY: FLOATING BODY

DEPTH: QUASI-CONCAVITY

hD is always quasi-concave, i.e. for each $\delta \in [0, 1]$ $\left\{x \in \mathbb{R}^d : hD(x; P) \ge \delta\right\}$ is a convex set



DEPTH: LEVEL SETS

It holds true that

$$\left\{x \in \mathbb{R}^d : hD(x; P) \ge \delta\right\} = \bigcap \left\{H \in \mathcal{H} : P(H) \ge 1 - \delta\right\}$$



Proposition (Grünbaum, 1960) Let $K \subset \mathbb{R}^d$ be a convex body, vol (K) = 1. Then

$$hD(\mathsf{E}K;K) \geq \left(\frac{d}{d+1}\right)^d.$$

APPLICATIONS

DE GÉOMÉTRIE

ΕТ

DE MÉCHANIQUE;

A LA MARINE, AUX PONTS ET CHAUSSÉES, ETC.,

POUR FAIRE SUITE

AUX DÉVELOPPEMENTS DE GÉOMÉTRIE,

PAR CHARLES DUPIN,

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PARIS,

BACHELIER, SUCCESSEUR DE M. V. COURCIER, LIBRAIRE, QUAI DES AUGUSTINS.

Definition (Dupin, 1822)

A convex body $K_{[\delta]}$ is called the floating body of $K \in \mathcal{K}^d$, if $\delta \in [0, \text{vol}(K)/2]$ and each supporting hyperplane of $K_{[\delta]}$ cuts off a set of volume δ from K.



















Floating body of K for $\delta = 0.3$



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$$\Omega(K) = \int_{\partial K} \kappa(x)^{1/(d+1)} d\mu(x),$$

where

- \succ K is a convex body of class C_2^+ ,
- \blacktriangleright ∂K is the topological boundary of K,
- \blacktriangleright κ is the Gauss-Kronecker curvature of K, and
- μ is the surface area measure of K
 (d 1-dimensional Hausdorff measure on ∂K).

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Proposition (Blaschke, 1923)
It holds true that
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$$\Omega\left(K\right)^{d+1} \le d^{d+1}\kappa_d^2 \operatorname{vol}\left(K\right)^{d-1}$$

with equality only for K ellipsoid. Here, κ_d is the volume of the unit ball in \mathbb{R}^d .

Ellipsoids have the largest affine surface area.

Proposition (Blaschke, 1923) If for δ small the floating body of K exists, then for $c_d = 2 (\kappa_{d-1}/(d+1))^{2/(d+1)}$

$$\Omega(K) = \lim_{\delta \to 0} c_d \frac{\operatorname{vol}(K) - \operatorname{vol}(K_{[\delta]})}{\delta^{2/(d+1)}}.$$

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Definition (Schütt and Werner, 1990)

Let $K \subset \mathbb{R}^d$ be a convex body and $\delta \in [0, \text{vol}(K)/2]$. The convex floating body of *K* associated with δ is given by

$$K_{\delta} = \bigcap \{ H \in \mathcal{H} : \text{ vol } (K \cap H) \ge 1 - \delta \}.$$

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Proposition (Schütt and Werner, 1990) K_{δ} always exists. If $K_{[\delta]}$ exists, then $K_{[\delta]} = K_{\delta}$. Further,

$$\Omega(K) = \lim_{\delta \to 0} c_d \frac{\operatorname{vol}(K) - \operatorname{vol}(K_{\delta})}{\delta^{2/(d+1)}}.$$

CONVEX FLOATING BODY

Convex floating body of *K* always exists.



Definition (Bárány and Larman, 1988) For $K \in \mathcal{K}^d$ and $x \in K$ define

 $\nu(X) = \min \left\{ \operatorname{vol} \left(K \cap H \right) : X \in H, H \in \mathcal{H} \right\}.$

Similar functions were considered also earlier (Neumann, 1945; Rado, 1946; Grünbaum, 1960; Leichtweiß, 1986...)

Rado (1946) defines ν in \mathbb{R}^2 for "densities" $f(x, y) \colon \mathbb{R}^2 \to [0, \infty)$.

Fresen (2012) writes about "multivariate quantiles" given by ν .

Proposition (Schütt and Werner, 1990) $\Omega(K) = \lim_{\delta \to 0} c_d \frac{\operatorname{vol}(K) - \operatorname{vol}(K_{\delta})}{\delta^{2/(d+1)}}.$

Problem: For measures $P \in \mathcal{P}(\mathbb{R}^d)$ one may be interested in the behaviour of the function

$$\delta \mapsto 1 - P(\{hD(\cdot; P) \ge \delta\}) = P(\{hD(\cdot; P) < \delta\})$$

as $\delta \rightarrow 0$. How to interpret that rate of convergence?

Proposition (Fresen, 2013)

Let $P \in \mathcal{P}(\mathbb{R}^d)$ be log-concave, and let X_1, \ldots, X_n be a random sample from P. Then co (X_1, \ldots, X_n) for $n \to \infty$ "approximates" the convex floating body of measure P corresponding to $\delta = 1/n$.

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- The depth determines the rate of convergence, and the shape of the convex hull of random samples.
- > Affine surface area describes the "tail complexity" of P.

$$hD_{1/n}(P) \approx \operatorname{co}(X_1, \ldots, X_n)$$
 as $n \to \infty$



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$$hD_{1/n}(P) \approx \operatorname{co}(X_1, \ldots, X_n)$$
 for $n = 10$



$$hD_{1/n}(P) \approx co(X_1, ..., X_n)$$
 for $n = 100$



$$hD_{1/n}(P) \approx co(X_1, ..., X_n)$$
 for $n = 1000$



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$$hD_{1/n}(P) \approx co(X_1, ..., X_n)$$
 for $n = 5000$



DEPTH: ASYMPTOTIC NORMALITY

$\sqrt{n}(hD(x; P_n) - hD(x; P))$ is asymptotically normal

 \iff the contour of $hD(\cdot; P)$ is smooth in x



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PROBLEM: SMOOTHNESS OF DEPTH

Elliptically symmetric distributions have elliptical depth contours



Problem (Massé and Theodorescu, 1994)

Does there exist a non- α -symmetric distribution with smooth depth contours?

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Proposition (Meyer and Reisner, 1991) Let K be a symmetric convex body. Then

- > K_{δ} is symmetric and strictly convex,
- ▶ if K is smooth and strictly convex, then K_{δ} is C_2^+ .

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Open problem: What can be said about general distributions with well-behaved densities?

Unit ball in L^{∞} — no smooth depth contours



Smoothness: Rectangle

Unit ball in L^{∞} — no smooth depth contours



Unit ball in L^{10} — all depth contours smooth



Problem (Schütt and Werner, 1994)

Let $c, \delta > 0$ and $K = c K_{\delta}$. Is then K an ellipsoid?

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Let $c, \delta > 0$ and $K = c K_{\delta}$. Is then K an ellipsoid?

► If
$$K = c_n K_{\delta_n}$$
 for $\delta_n \to 0$ (Schütt and Werner, 1994).

► If K is C_2^+ and $K = c K_\delta$ for $\delta < \delta(K)$ (Stancu, 2006, 2009).

► If
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 for $\delta < \delta(K)$ (Werner and Ye, 2011).

In general still an open problem.

Conjecture (Struyf and Rousseeuw, 1998) For any $P, Q \in \mathcal{P}(\mathbb{R}^d)$, $P \neq Q$ there exists $x \in \mathbb{R}^d$ such that $hD(x; P) \neq hD(x; Q)$.

Partial positive answers: This is true if

- P and Q are absolutely continuous with a compact support (Koshevoy, 2001);
- P and Q are empirical (Koshevoy, 2002);
- P is atomic (Cuesta-Albertos and Nieto-Reyes, 2008);
- ▶ P and Q have smooth densities (Hassairi and Regaieg, 2008);
- > P and Q have smooth depth contours (Kong and Zuo, 2010).

Proposition (Hassairi and Regaieg, 2008, Theorem 3.2) Let $P \in \mathcal{P}(\mathbb{R}^d)$ have a density that is smooth in the interior of its connected support. Then for any $H \in \mathcal{H}$

$$P(H) = \begin{cases} \sup_{x \in \partial H} hD(x; P) & \text{if } x_P \notin H, \\ 1 - \sup_{x \in \partial H} hD(x; P) & \text{if } x_P \in H, \end{cases}$$

where x_P is the halfspace median of P.

 \implies *P* is characterized by its depth

HASSAIRI AND REGAIEG'S CHARACTERIZATION

Not true — can be valid only for *P* halfspace symmetric.

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Definition A convex body $P_{[\delta]}$ is called the floating body of a measure $P \in \mathcal{P}(\mathbb{R}^d)$, if $\delta \in [0, 1/2]$ and each supporting hyperplane of $P_{[\delta]}$ cuts off a set of probability δ .

Proposition (Nagy, Schütt, Werner, 2017) Let $P \in \mathcal{P}(\mathbb{R}^d)$ satisfy **(C)**, and let x_P be the halfspace median of P. Then the following are equivalent

- ► For each $\delta \in (0, 1/2)$ the floating body of P exists.
- ▶ P satisfies (S), and for each $H \in H$

$$P(H) = \begin{cases} \sup_{x \in \partial H} hD(x; P) & \text{if } x_P \notin H, \\ 1 - \sup_{x \in \partial H} hD(x; P) & \text{if } x_P \in H. \end{cases}$$

In particular, P is characterized by its depth.

Comments:

- For any symmetric, full-dimensional, κ-concave
 P ∈ P (ℝ^d) with κ > −1 the floating bodies P_[δ] exist for all δ ∈ (0, 1/2); (Meyer and Reisner, 1991; Ball, 1991; Bobkov, 2010)
 Under (C):
 - P has smooth depth \implies (S) and $P_{[\delta]}$ exist for all δ \implies P is H-symmetric

Conjecture (Struyf and Rousseeuw, 1998) For any $P, Q \in \mathcal{P}(\mathbb{R}^d)$, $P \neq Q$ there exists $x \in \mathbb{R}^d$ such that $hD(x; P) \neq hD(x; Q)$.

Partial positive answers: This is true if

 P and Q are empirical (Struyf and Rousseeuw, 1999; Koshevoy, 2002; Laketa and Nagy, 2021);
 if all Dupin's floating bodies of P exist (Hassairi, Regaieg, 2008; Kong, Zuo, 2010; Nagy, Schütt, Werner, 2019).

Conjectured positive answer.

(Cuesta-Albertos and Nieto-Reyes, 2008; Kong and Mizera, 2012)

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Proposition (Nagy, 2021)

For any d > 1 there are two measures in $\mathcal{P}(\mathbb{R}^d)$ with the same depth.

Recall that $P \in \mathcal{P}(\mathbb{R}^d)$ is α -symmetric (Eaton, 1981) if

$$\psi(t) = \int_{\mathbb{R}^d} \exp\left(\mathrm{i}\left\langle t, x \right\rangle\right) \,\mathrm{d}\, P(x) = \xi\left(\left\| t \right\|_{\alpha}\right) \quad \text{ for all } t \in \mathbb{R}^d$$

for some $\xi \colon \mathbb{R} \to \mathbb{R}$. For $X = (X_1, \ldots, X_d) \sim P$, these measures satisfy

$$\langle X, u \rangle \stackrel{d}{=} \|u\|_{\alpha} X_1$$
 for all $u \in \mathbb{S}^{d-1}$.

For the depth of α -symmetric P

$$hD(x; P) = \inf_{u \in \mathbb{S}^{d-1}} P(\langle X, u \rangle \le \langle x, u \rangle) = \inf_{u \in \mathbb{S}^{d-1}} P(||u||_{\alpha} X_{1} \le \langle x, u \rangle)$$
$$= P\left(X_{1} \le \inf_{u \in \mathbb{S}^{d-1}} \langle x, u \rangle / ||u||_{\alpha}\right) = F_{1}\left(-||x||_{\beta}\right)$$

for β the conjugate exponent to α , and F_1 the c.d.f. of X_1 .

Fix $\gamma \in (0, 1)$ and take $\psi_{\alpha}(t) = \exp\left(-\|t\|_{\alpha}^{\gamma}\right)$ for $\gamma \leq \alpha \leq 1$. Then

- > Measure P_{α} with characteristic function ψ_{α} exists (Lévy, 1937);
- ▶ The conjugate index to $\alpha \leq 1$ is $\beta = \infty$; and
- ► For the characteristic function of X_1 with $X \sim P_{\alpha}$ we have

$$\mathsf{E}\exp\left(\operatorname{i} t X_{1}
ight)=\exp\left(-\left|t\right|^{\gamma}
ight)$$
 for all $t\in\mathbb{R}$,

i.e. F_1 does not depend on α .

All $P_{\alpha} \in \mathcal{P}(\mathbb{R}^d)$ have the same depth

 $hD(x; P_{\alpha}) = F_1(-\|x\|_{\infty}) \text{ for all } x \in \mathbb{R}^d.$
$\gamma = 1/2$: the density of P_{α} with $\alpha = 1$ (left) and $\alpha = 1/2$ (right).



What we know:

- Halfspace depth and the floating body are the same concept.
- The depth describes the asymptotics of the convex hull of samples.
- > Depth does not characterize distributions.

What we do not know:

- > When are floating bodies of measures Dupin's, or smooth?
- How many barycentric hyperplanes pass through medians?
- ► How large can the median sets be?
- > When does the depth characterize distributions?

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