

# PRIMUS GeMS: SOME OPEN PROBLEMS

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**Basic definitions and notation.** Let  $\mathcal{P}(\mathbb{R}^d)$  be the set of all probability measures on  $\mathbb{R}^d$ . For  $P \in \mathcal{P}(\mathbb{R}^d)$  and  $x \in \mathbb{R}^d$ , the halfspace (Tukey) depth [6] of  $x$  with respect to (w.r.t.)  $P$  is defined as

$$hD(x; P) = \inf_{\mathfrak{H} \in \mathcal{H}(x)} P(\mathfrak{H}),$$

where  $\mathcal{H}(x)$  is the set of all halfspaces whose boundary hyperplane passes through  $x$ . The halfspace depth quantifies the “centrality” of a point  $x$  w.r.t. the distribution  $P$ . For  $\alpha \geq 0$ , consider the upper level set of the depth

$$hD_\alpha = \{x \in \mathbb{R}^d : hD(x; P) \geq \alpha\}.$$

This collection of the so-called depth regions  $hD_\alpha$ , for  $\alpha \in [0, 1]$ , constitutes a generalisation of quantiles to multivariate probability measures. The point (or a set of points) that maximizes the depth w.r.t.  $P$  is the generalised (halfspace) median of  $P$  in  $\mathbb{R}^d$ . For  $\alpha$  high (near  $1/2$ ), region  $hD_\alpha$  forms the locus of points in the “centre” of the distribution  $P$ . For  $P \in \mathcal{P}(\mathbb{R}^d)$  uniform on a convex body  $K \subset \mathbb{R}^d$ , the depth regions  $hD_\alpha$  coincide with the so-called floating bodies of  $K$  studied in geometry [30, 23, 34].

An array of open problems regards generalisations of results known for floating bodies (uniform distributions on those bodies) in  $\mathbb{R}^d$  to “reasonable” classes of measures in  $\mathcal{P}(\mathbb{R}^d)$ . Often, it is easy to show that a given property does not hold true for all measures in  $P \in \mathcal{P}(\mathbb{R}^d)$ . In that case, it is always interesting to see whether the property can hold true at least for  $P$  that:

- has finite moments,
- has a density  $f$  (w.r.t. the Lebesgue measure),
- its density is bounded, continuous, or smooth,
- is (in some sense) symmetric,
- its density  $f$  is unimodal, log-concave, or quasi-concave, etc.

Most of the problems presented in this text is examined in greater detail in the survey paper [30].

1. **Characterisation by depth.** Let  $P, Q \in \mathcal{P}(\mathbb{R}^d)$  be two different probability measures. Does there exist a point  $x \in \mathbb{R}^d$  such that  $hD(x; P) \neq hD(x; Q)$ ? We know that this characterisation result holds true under additional assumptions:

- if  $P$  is has a finite number of atoms [22];
- if the boundaries of the depth regions  $hD_\alpha$  are smooth for both  $P$  and  $Q$  for all  $\alpha \in [0, 1/2)$  [21].

We know that the general conjecture is not valid [28]. Though, all the available examples of different distributions with the same depth that are distributions without a finite first moment (expectation). Is the existence of the expectation sufficient for the depth to characterize the distribution? Under which conditions are absolutely continuous probability distributions

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*Date:* February 5, 2019.

characterised by their depth? Is the uniform distribution on a triangle characterized by its depth?

Can we, for a given halfspace  $\mathfrak{H} \subset \mathbb{R}^d$ , determine  $P(\mathfrak{H})$  only from the depth of  $P$  at all points in  $\mathbb{R}^d$ ?

**2. Centroids of the cuts of a measure.** For a point  $x \in \mathbb{R}^d$  and a measure  $P$  we say that a hyperplane  $H \subset \mathbb{R}^d$  minimizes the depth at point  $x \in \mathbb{R}^d$ , if  $x \in H$  and  $P(\mathfrak{H}) = hD(x; P)$  for one of the halfspaces  $\mathfrak{H}$  whose boundary is  $H$ . Halfspace  $\mathfrak{H}$  is then called a minimizing halfspace of  $x$ . For a random vector  $X \sim P$  uniformly distributed on a convex body  $K$  it holds that at each  $x \in K$  there exists a minimizing hyperplane, and for each hyperplane  $H$  that minimizes the depth at  $x \in K$  we have that  $x$  is the centroid of a cut of the body  $K$  by the hyperplane  $H$  [18]. For  $P \in \mathcal{P}(\mathbb{R}^d)$  with continuous density positive on a convex set, a variant of this result is proved in [19, Theorem 3.1]. Does a version of this theorem hold true also for general measures  $P \in \mathcal{P}(\mathbb{R}^d)$ ?

**3. Cuts of a measure through its centroid.** For  $P \in \mathcal{P}(\mathbb{R}^d)$  with a density, we know that there exists a collection minimizing halfspaces of  $x_P$  whose union is  $\mathbb{R}^d$  [31, Propositions 8 and 12]. By Problem 2, for reasonable measures  $P$ , for each bounding hyperplane  $H$  of such a halfspace, the centroid of the cut of  $P$  by  $H$  is  $x_P$ .

Does there always exist a collection of  $d + 1$  hyperplanes  $H_i \ni x_P$  such that  $x_P$  is the centroid of  $H_i \cap K$  for each  $i = 1, \dots, d + 1$ ? Is there always a collection  $H_i, i = 1, \dots, d + 1$  of hyperplanes passing through the expectation (the centroid)  $\mathbb{E}X$  of a reasonable measure  $P \in \mathcal{P}(\mathbb{R}^d)$ ,  $X \sim P$ , such that  $\mathbb{E}X = \mathbb{E}(X | H_i)$  for each  $H_i, i = 1, \dots, d + 1$ ? In the special case of  $P$  uniform on a convex body  $K$ , this is the open problem A8 from the book [5].

**4. Grünbaum's inequality.** For  $X \sim P \in \mathcal{P}(\mathbb{R}^d)$  uniform on a convex body  $K \subset \mathbb{R}^d$  and  $x = \mathbb{E}X$  the centroid of  $K$  it holds that [17]

$$(1) \quad hD(x; P) \geq \left( \frac{d}{d+1} \right)^d \geq \exp(-1) > 0.36.$$

This inequality is interesting, because the lower bound does not depend on the dimension  $d$ . Under what conditions does such a result hold true also for measures? For log-concave measures, analogous inequalities are derived in [3, Section 5.2] — can these results be extended to other classes of reasonable measures?

Does an inequality of type (1) hold true also for measures without the condition  $x = \mathbb{E}X$ ? That is, find the broadest class of measures  $\mathcal{Q}$  such that

$$\inf_{P \in \mathcal{Q}} \sup_{x \in \mathbb{R}^d} hD(x; P) \geq c > 0$$

for some  $c > 0$ .

**5. Funk's characterisation of symmetry.** We say that a measure  $P \in \mathcal{P}(\mathbb{R}^d)$  is halfspace symmetric around  $x \in \mathbb{R}^d$  if  $hD(x; P) \geq 1/2$ .

For a convex body  $K \subset \mathbb{R}^d$ ,  $K$  is symmetric around  $x \in K$  (in the sense  $K - x = -(K - x)$ ) if and only if the uniform measure  $P$  on  $K$  is halfspace symmetric around  $x$  [14, 33]. This result is known as the Funk theorem.

Let  $P \in \mathcal{P}(\mathbb{R}^d)$  be halfspace symmetric around  $x \in \mathbb{R}^d$  such that  $P(\{x\}) = 0$ . Then, for  $X \sim P$ , the distributions of the random vectors  $(X - x)/\|X - x\|$  and  $-(X - x)/\|X - x\|$  are identical [32, Theorem 2]. This implies a general version of the Funk theorem for measures. As far as we can tell, this theorem is not known in geometry.

Under what conditions imposed on the measure  $P$  (i.e. the existence and continuity of the density  $f$ , its quasi-concavity, or log-concavity) does it hold true, that the halfspace symmetry

around  $x \in \mathbb{R}^d$  is equivalent with the symmetry of its density  $f$  around  $x$  (i.e.  $f(\cdot - x) \equiv f(x - \cdot)$ )?

**6. Smoothness of depth contours.** Let  $X_1, X_2, \dots, X_n$  be a random sample from the distribution  $P$  with a density. Denote by  $P_n \in \mathcal{P}(\mathbb{R}^d)$  the empirical measure of this random sample<sup>1</sup>. We know that for a given  $x \in \mathbb{R}^d$ , the distribution of the random variable  $\sqrt{n}(hD(x; P_n) - hD(x; P))$  is asymptotically normal if and only if there is a unique hyperplane minimizing the depth (w.r.t.  $P$ ) at  $x$  [24]. The last condition is equivalent with the smoothness of the boundary of the depth region  $hD_\alpha$  for  $\alpha = hD(x; P)$  at  $x$ . Under what conditions on  $P$  and  $x$  can we guarantee that this is fulfilled?

Under what conditions on  $P$  can we guarantee that for all points  $x \in \mathbb{R}^d$  (except for the halfspace median of  $P$ ) the asymptotic distribution of  $\sqrt{n}(hD(x; P_n) - hD(x; P))$  is normal? The only known example of such distributions in statistics is the class of elliptically symmetric distributions (e.g. multivariate normal distributions), for which the depth regions  $hD_\alpha$  are concentric ellipsoids, and, a bit more generally, a class of very special distributions called  $\alpha$ -symmetric distributions [11, Chapter 7]. Another example of such distributions from geometry are the uniform distributions on symmetric, strictly convex bodies with smooth boundaries [25]. For which other measures does this condition hold true?

**7. Detection of rough points.** In practice the measure  $P$  is unknown, and we are given only the empirical measure  $P_n$  of the random sample  $X_1, X_2, \dots, X_n$  from  $P$ . Is it possible, using only  $P_n$ , to detect (test) whether for a given point  $x \in \mathbb{R}^d$  the contour of the depth  $hD(\cdot; P)$  is smooth at  $x$  as in Problem 6?

**8. Shape and orientation of depth contours.** As shown by Milman and Pajor [27, page 104], for  $P$  uniform on a (symmetric) convex body  $K \subset \mathbb{R}^d$ , each set  $hD_\alpha$  is homothetic to a fixed ellipsoid whose orientation depends only on the variance matrix of  $P$ . For log-concave measures  $P$ , a generalization of this theorem is mentioned in [12]. Under what conditions is it possible to extend this theorem to general measures  $P$ ?

Let  $P$  be an isotropic measure<sup>2</sup> with a positive density on  $\mathbb{R}^d$ . Does it hold true that for each  $r > 0$  there exists  $\alpha > 0$  such that  $B(r) \subset hD_\alpha$ , where  $B(r) = \{x \in \mathbb{R}^d : \|x\| < r\}$ ?

**9. Gnedenko's law of large numbers.** For  $P \in \mathcal{P}(\mathbb{R}^d)$  log-concave and  $X_1, X_2, \dots, X_n$  a random sample from  $P$ , Fresen [13] shows that the convex hull  $\text{co}(X_1, X_2, \dots, X_n)$  of the observations does, for  $n \rightarrow \infty$ , with large probability "behave like" the set  $hD_\alpha$  with  $\alpha = 1/n$ . Does this result hold true for broader classes of measures? Is it possible to sharpen it<sup>3</sup>? Does this result have applications in statistics, e.g. in the analysis of multivariate extremes?

**10. Probabilistic volumes of the depth regions.** Is it possible, from the depth of all points in  $\mathbb{R}^d$ , to determine  $P(hD_\alpha)$ ? Can we (for reasonable measures) at least well estimate this probability?

What is the relation between the index  $\alpha$  and the characteristics of the set  $hD_\alpha$  (probability  $P(hD_\alpha)$ , volume  $\text{vol}(hD_\alpha)$ , the diameter of  $hD_\alpha$ )?

<sup>1</sup>The uniform distribution concentrated in the sample points.

<sup>2</sup> $\mathbb{E}X = 0$ , and the variance matrix  $X \sim P$  is a multiple of an identity.

<sup>3</sup>The estimates of the distances between sets in [13] are considered only w.r.t. a very special metric in the space of convex bodies.

11. **Affine surface area for measures.** For  $P$  uniform on a convex body  $K$  the limit

$$\lim_{\alpha \rightarrow 0^+} \frac{1 - P(hD_\alpha)}{\alpha^{2/(d-1)}}$$

is proportional to the affine surface area of the body  $K$  [34]. Is it possible to extend this result to measures? What are the properties, and the interpretation of this characteristic in  $\mathcal{P}(\mathbb{R}^d)$ ?

12. **Affine invariant points.** A continuous mapping  $p$  from the space of convex bodies in  $\mathbb{R}^d$  (equipped with the Hausdorff metric) to  $\mathbb{R}^d$  that is equivariant w.r.t. non-singular affine transformations of  $\mathbb{R}^d$  is called an affine invariant point [18, 26]. Examples of affine invariant points are the centroid, or the centre of the John ellipsoid of  $K$  (the ellipsoid of maximal volume that is contained in  $K$ ). Is the halfspace median of a convex body an affine invariant point? Is it possible to consider affine invariant points also w.r.t. probability measures?

13. **Computation of depth.** Finding the depth of a point  $x \in \mathbb{R}^d$  w.r.t. the empirical measure  $P_n$  of a random sample for larger values of  $d$  and  $n$  can be computationally very expensive. The best known exact algorithms have complexity  $\mathcal{O}(n^{d-1} \log(n))$  [10]. For a recent survey on related results see Chapter 58 in the book [16]. Usually, the exact computations of the halfspace medians, and the depth regions, are even more involved. Is it possible to speed up these algorithms? Can we, in a fast way, compute the depth w.r.t. a measure given by a density? A trivial approach to the last problem is described in [20].

14. **Approximation of depth.** In practice, for larger  $d$  we often resort to the approximation of the depth  $hD(x; P)$  (or  $hD(x; P_n)$ ) using the function

$$(2) \quad hD_N(x; P) = \min_{i=1, \dots, N} P(\{y \in \mathbb{R}^d : \langle x, U_i \rangle \leq \langle y, U_i \rangle\}),$$

where  $U_1, \dots, U_N$  is a random sample from (the uniform) distribution on the unit sphere in  $\mathbb{R}^d$ . As  $N \rightarrow \infty$  we know that  $hD_N(x; P) \rightarrow hD(x; P)$  almost surely [9, Section 6]. Does such an approximation hold true also uniformly over all  $x \in \mathbb{R}^d$ ? How large  $N$  do we need to take in order to achieve a sufficiently good approximation of the true depth? First results in this direction can be found in [29].

15. **Depth in non-Euclidean spaces.** For a definition of the halfspace depth in a general space  $M$  it suffices to introduce the concept of halfspaces, as a system of some measurable subsets of  $M$ . In the literature, the depth has been introduced in this way on, e.g. the unit sphere [35], or in general metric spaces [4]. Similarly, in geometry, the study of floating bodies on manifolds and other general structures is already under way [1, 2]. Which properties of the depth in  $\mathbb{R}^d$  hold true also without the assumption of linearity of the space  $M$ ?

16. **Depth in infinite-dimensional spaces.** Let  $B$  be a general Banach space, which can be equipped with halfspaces of the form

$$\mathfrak{H} = \mathfrak{H}(y, \varphi) = \{x \in B : \varphi(x) \leq \varphi(y)\},$$

where  $y \in B$  and  $\varphi$  is a bounded linear functional from the dual space of  $B$ . With such halfspaces it is possible to formally define the halfspace depth also for measures  $P \in \mathcal{P}(B)$ . Though, it appears that in that case  $hD$  can degenerate, i.e. assign  $hD(x; P) = 0$  to (almost) all  $x \in B$  also for very reasonable measures  $P$  [8, 15]. On the other hand, inequalities of type (1) suggest that for special measures, some points can still have positive depth, also in  $B$  of infinite dimension.

Does it make sense to consider the halfspace depth also in infinite-dimensional spaces? Can we describe the locus of points for which  $hD(x; P) > 0$  in a general space  $B$ ? Is it possible to resolve the problem of the degeneration of the depth?

**17. Existence of Dupin's floating bodies.** For a convex body  $K \subset \mathbb{R}^d$  of unit volume and  $\alpha > 0$  small, we say that the Dupin's floating body of  $K$  is the convex set  $K_{[\alpha]}$  such that each supporting hyperplane of  $K_{[\alpha]}$  cuts off a set of volume  $\alpha$  from  $K$  [7]. Dupin's floating body may not exist. For instance,  $K_{[\alpha]}$  does not exist for  $K$  the triangle in  $\mathbb{R}^2$  for any  $\alpha > 0$ . Though, if  $K_{[\alpha]}$  exists, then  $K_{[\alpha]} = hD_\alpha$  for  $P$  the uniform distribution on  $K$  [34]. In other words, if the Dupin's floating body of  $K$  exists, then it coincides with the floating body of  $K$ . For a measure  $P \in \mathcal{P}(\mathbb{R}^d)$ , one can define Dupin's floating bodies analogously. In connection with Problem 1, it appears that [30, Theorem 34] if all Dupin's floating bodies of  $P$  exist for all  $\alpha \in (0, 1/2)$ , then the measure  $P$  is characterised by its depth, and  $P(\mathfrak{H})$  is given either by  $c = \sup_{x \in \partial \mathfrak{H}} hD(x; P)$ , or by  $1 - c$  for any halfspace  $\mathfrak{H} \subset \mathbb{R}^d$ . In connection with Problem 6, if all depth contours of  $P$  are smooth, then all Dupin's floating bodies of  $P$  exist for all  $\alpha \in (0, 1/2)$ .

In Bobkov [3, Theorem 6.1] it is shown that for symmetric, full-dimensional,  $\kappa$ -concave<sup>4</sup> probability measures  $P$  with  $\kappa > -1$ , all Dupin's floating bodies of  $P$  exist. Can the condition  $\kappa > -1$  be dropped? Does there exist other probability measures  $P$  whose Dupin's floating bodies exist?

**18. Strict convexity of  $hD_\alpha$ .** For  $P$  a uniform distribution on a convex body,  $hD_\alpha$  is always a strictly convex set. This follows from the partial positive result stated in Problem 2. If  $P$  is such that  $X \sim P$  does not have an expectation,  $hD_\alpha$  may fail to be strictly convex. Also, if  $P$  is distributed uniformly on a non-convex set in  $\mathbb{R}^d$ , there may exist  $hD_\alpha$  whose boundary contains a line segment. Under which conditions are all depth regions of  $P \in \mathcal{P}(\mathbb{R}^d)$  strictly convex? Must all Dupin's floating bodies of a measure be strictly convex?

**19. Homothety conjecture.** For  $K$  an ellipsoid in  $\mathbb{R}^d$ , all (Dupin's) floating bodies of  $K$  are concentric ellipsoids with the same centre and the same orientation as  $K$ . Is it true that if, for some convex body  $K \subset \mathbb{R}^d$ , some floating body  $K_\delta$  is an ellipsoid, then  $K$  must be an ellipsoid as well? This problem is called the homothety conjecture [36, 37].

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<sup>4</sup>Measure  $P \in \mathcal{P}(\mathbb{R}^d)$  is called  $\kappa$ -concave for  $-\infty \leq \kappa \leq \infty$  if  $P(tA + sB) \geq (tP(A)^\kappa + sP(B)^\kappa)^{1/\kappa}$  for all  $A, B \subset \mathbb{R}^d$  Borel,  $s, t > 0$ ,  $s + t = 1$ . Condition  $\kappa > -1$  implies the existence of  $EX$  for  $X \sim P$ . For details see [3, Section 2].

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